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industrial robots have
stimulated the industrial
growth and freed
humans from tedious or
dangerous works in the
past few decades. In the
near future, robots will
revolutionize our daily
lives by moving from
controlled industrial
lines to unstructured
environments such as

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robots have their origins
in two preceding
technologies: numerical
control for machine
tools, and remote
manipulation.

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scheme to generate
control actions based on
stored data. Stored data
may include coordinate
data of

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remote manipulation
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definition of today's
industrial robot is that

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needed to work safely
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device a numerically controlled (NC) milling machine is not an industrial robot As [5, p3] says, if a mechanical device can be programmed to

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World Robotics
Industrial Robots uses
the words "shipments"

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and [installations] of industrial robots synonymously. This is a compromise between the theoretical idea of counting the actual installation of the robot at the customer's site and the practical data availability which often refers to the shipment of the robot.

~~1 Introduction~~

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□ This paper reports a few results of an ongoing research project that aims to explore ways to command an industrial robot using the human voice. This feature can be interesting with several industrial, laboratory and clean-room applications, where a

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close cooperation
between robots and
humans is desirable., □
A demonstration is
presented using two
industrial robots and a
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An industrial robot is a reprogrammable, multifunctional manipulator designed to move materials, parts, tools, or specialized devices through variable programmed motions for the performance of a variety of tasks. The technology of robotics is concerned with the

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design of the mechanical manipulator and the computer systems used to control it. It is also concerned with the industrial applications of robots, which are described below.

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Function is to hold, move, and apply a tool (called the end-effector) at the end of its structure towards a particular task with repetitive automation. Theory. Degrees of Freedom - is the number of rotation axes of the industrial robot. This number should be at least 6.

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An industrial robot is a programmable mechanical device that can perform multiple functions, including moving of tools, parts, materials, and

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specialized equipment
with the help of variable
programmed motions.
These robots are
typically used to carry
out highly repetitive,
hazardous, unsafe, or
unpleasant tasks.

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